Flight Instruments and Avionics

Objective

To understand the basic flight instruments used for flight, their limitations and biases, plus common failure modes.

Motivation

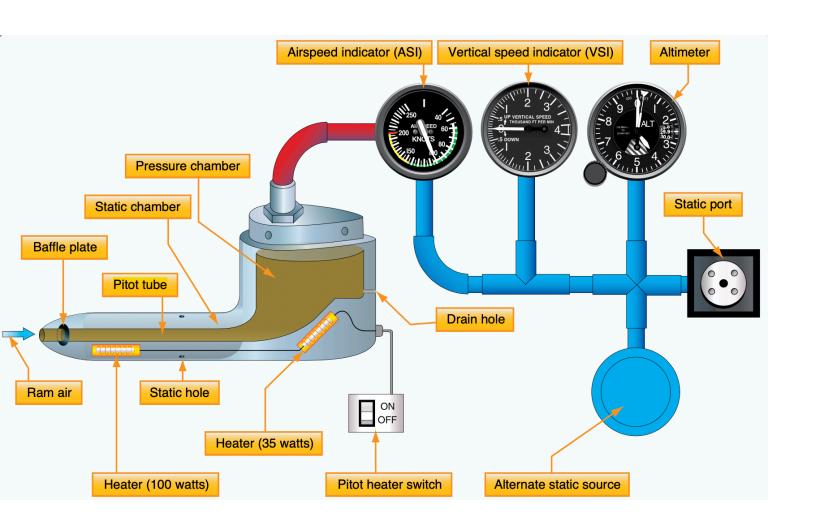
To a give a student an intuitive understanding of the operation of the flight instruments, and a sense of how they will behave if they malfunction.

Overview

- Pitot-Static instruments
 - Altimeter
 - Vertical Speed Indicator
 - Vertical Speed Indicator
 - Airspeed indicator
- Pitot-static port blockages
- Inclinometer

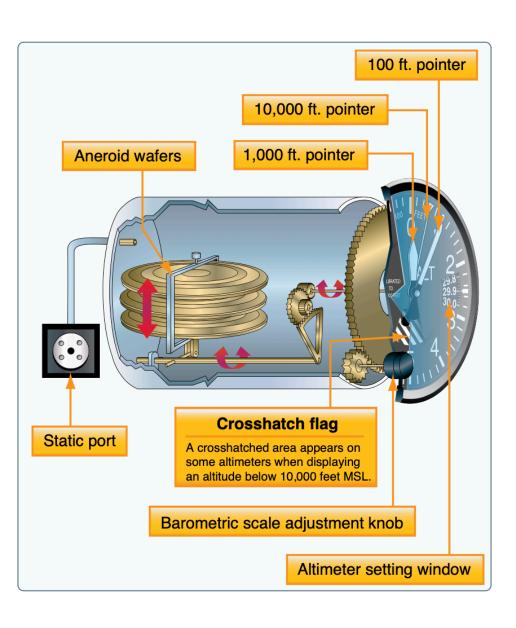
- Gyroscopic and vacuum Instruments
 - Attitude Indicator
 - Directional Gyro/Heading Indicator
 - Horizontal Situation Indicator (HSI)
- AHRS and EFIS Systems
- Vacuum System Failures
- Magnetic Compass
 - Compass errors





Pitot-Static instruments

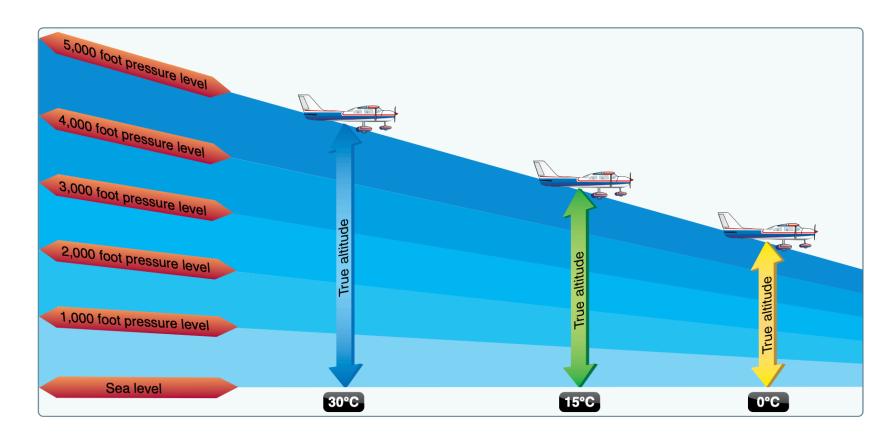
- Static port: Ambient air pressure
- Pitot tube: Ram air pressure, in the relative wind flow



Altimeter

- Converts barometric pressure into altitude
- Calibrated to the lapse rate of the standard atmosphere (2° per 1000', 1" Hg per 1000')
- Calibrated to the temperature of the standard atmosphere (15° @ S.L.)
- Kollsman window allows for calibrating the atmosphere indicator up and down
 - Window does have a set range

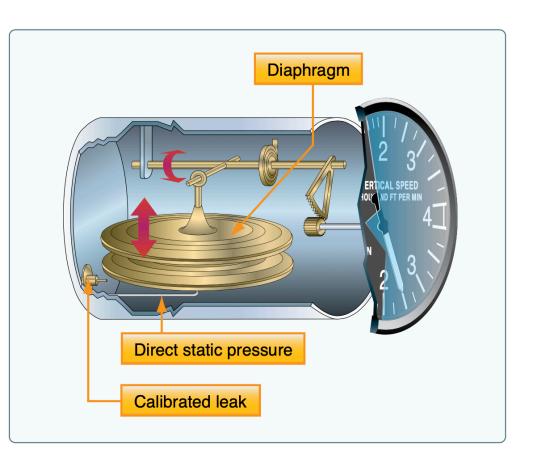
Nonstandard Temperature Errors



- Colder temperatures: "Compress" the column of air below, altimeter reads higher
- Hotter temperature: "Expand" the column of air below, altimeter reads lower

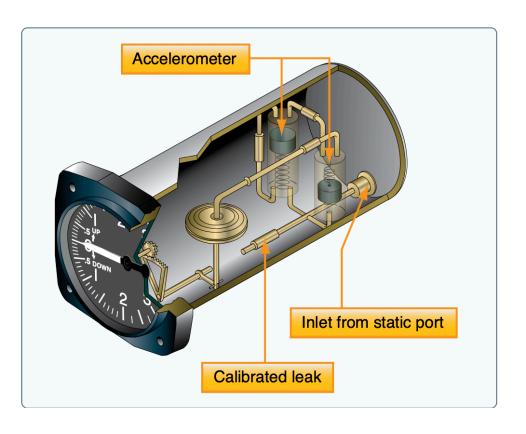
Types of Altitude

- Indicated altitude: Read from the altimeter
- **True** altitude: Vertical distance from mean sea level
- **Absolute** altitude: Vertical distance above terrain (AGL)
- Pressure altitude: Read from altimeter when set to 29.92"
 - Height in the standard atmosphere where the ambient pressure is found
- Density altitude: Pressure altitude corrected for nonstandard temperature



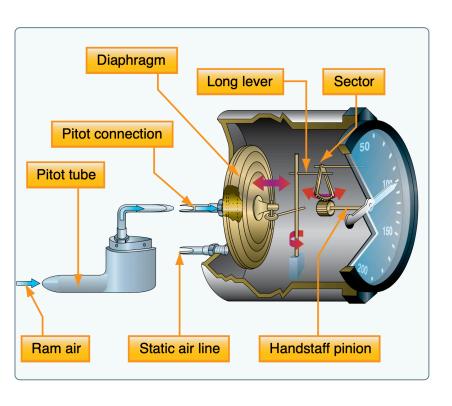
Vertical Speed Indicator

- Rate of change of the altitude/ambient pressure
- Will lag considerable with pressure alone



Instantaneous Vertical Speed Indicator (IVSI)

 Accelerometer weights help lead the indication before pressure changes



Airspeed indicator

- Airspeed = (Ram air pressure static pressure)
- Operates with a diaphragm

Types of Airspeed

- Indicated airspeed (IAS): Read from altimeter
- Calibrated airspeed (CAS): Calibrated for position/instrument errors
 - At slow airspeeds this may be several knots off
- True airspeed (TAS): CAS corrected for altitude and nonstandard temperature
- Ground speed (GS): Actual speed over the ground
 - TAS adjusted for wind

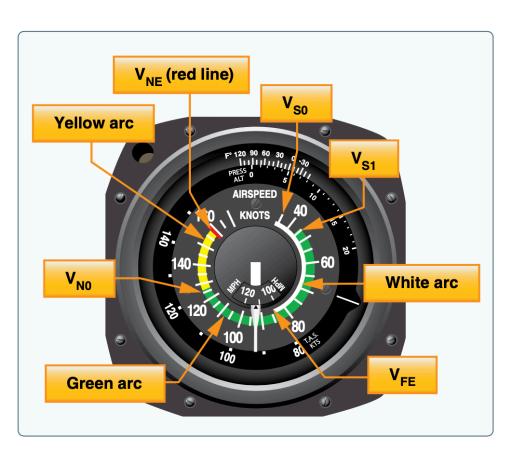
IAS vs CAS

CONDITIONS:

Power required for level flight or maximum power descent.

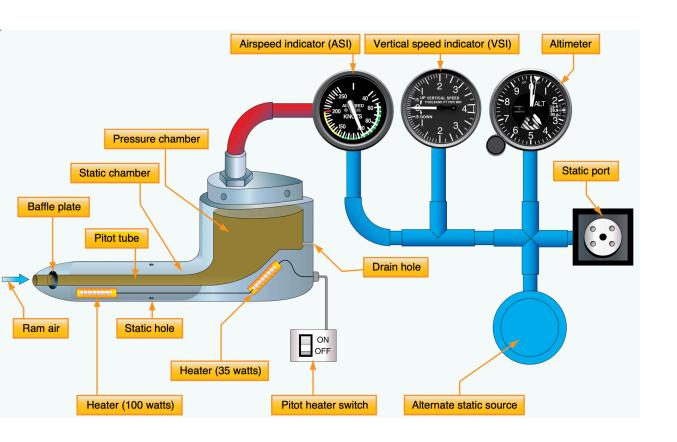
FLAPS UP													
KIAS KCAS	50 61	60 65	70 72	80 80	90 89	100 99	110 109	120 118	130 128	140 138	150 147	160 157	170 167
FLAPS 200													
KIAS KCAS	40 54	50 58	60 63	70 71	80 80	90 89	95 94		~				
FLAPS FULL													
KIAS KCAS	40 52	50 57	60 63	70 71	80 80	90 90	95 95						

Figure 5-1. Airspeed Calibration (Sheet 1 of 2)



Airspeed Indicator Markings

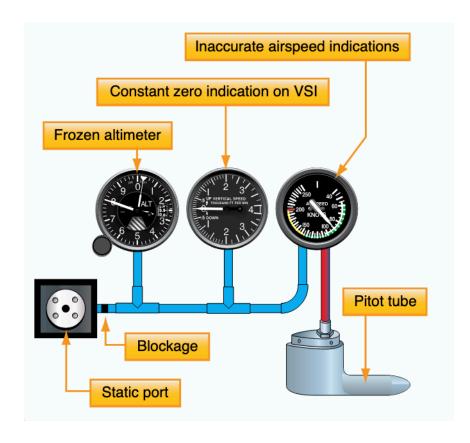
- V_{S0}: Stall speed in landing configuration
- V_{S1}: Stall speed in clean configuration
- V_{FE}: Flap extension speed (full flaps)
- V_{N0} : Maximum structural cruising speed (smooth air only)
- V_{NE}: Never exceed speed
- Note V_A is not marked



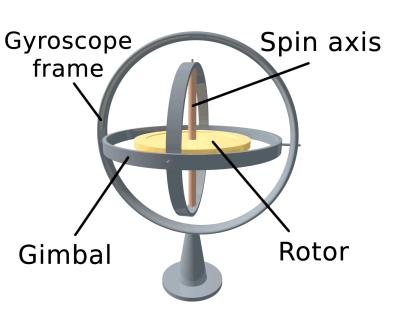
Pitot Blockages

- Ram air block: Airspeed reads 0
- Ram air + drain hole blocked:
 - Airspeed reads whatever it was when it was blocked
 - If you descend it'll read lower, higher if ascending

Static Port Blockages



- Most airplanes have an alternate static course
 - This will vent into the cockpit, which may have slightly lower pressure
- VSI will show no climb or descent
- A blocked static port will cause errors in the airspeed indicator
 - Recall Airspeed = RAM pressure static pressure
 - Airspeed is accurate at altitude where blockage occurred
 - Above the altitude, airspeed reads low
 - Below the altitude, airspeed reads high

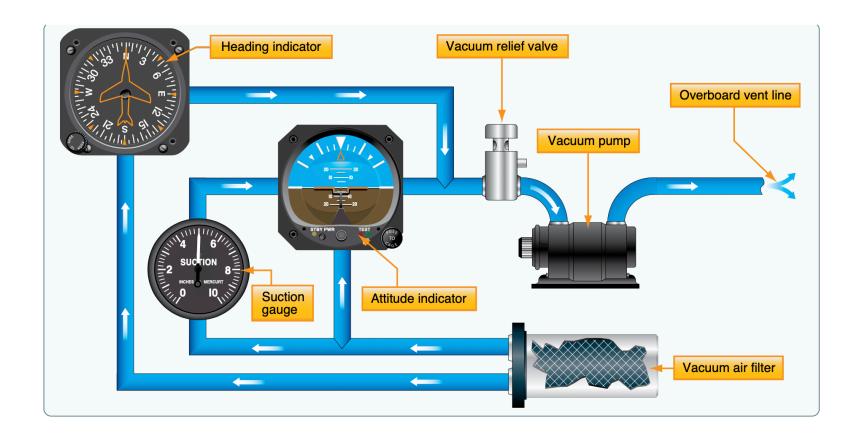


Gyroscopic Instruments

- Operate on the principle of gyroscopic stability
- Corollary: Bicycle wheel stability at low vs high speeds
- Mechanical flight instruments use a spinning rotor
 - Vacuum pump (engine-driven or electric)
 - Pressure
 - Electrical motor
- Aircraft rotates around the gyro

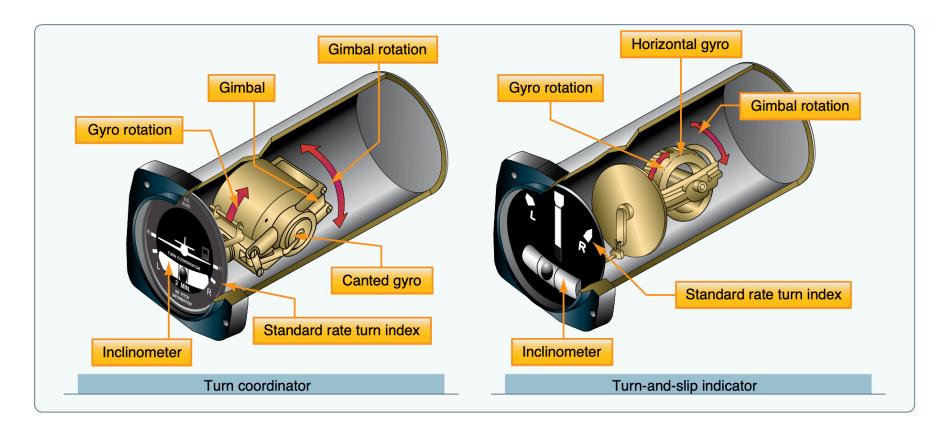


Vacuum Instruments



- In a standard "six pack":
 - Vacuum-driven gyroscopic system drive the attitude and heading indicators
 - Sometimes the turn coordinator

Turn Coordinator



- 1-axis gyro
- Indicates rate of yaw/turn rate around the vertical axis
- No primary bank information





Slipping turn

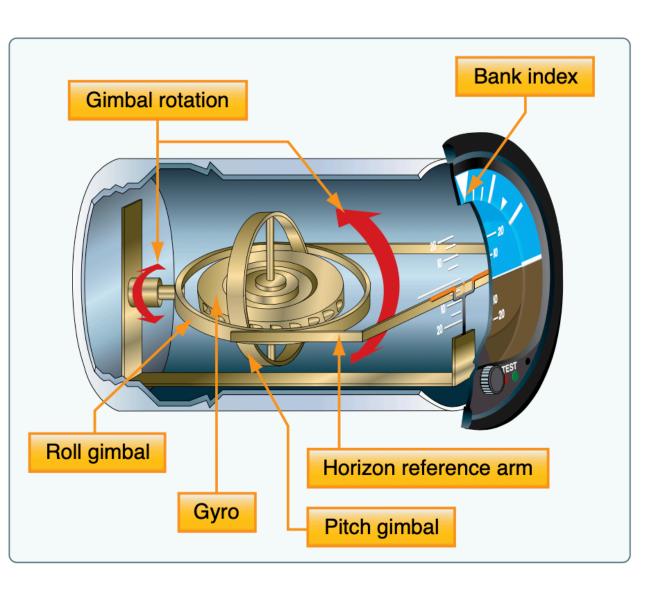
Skidding turn



Coordinated turn

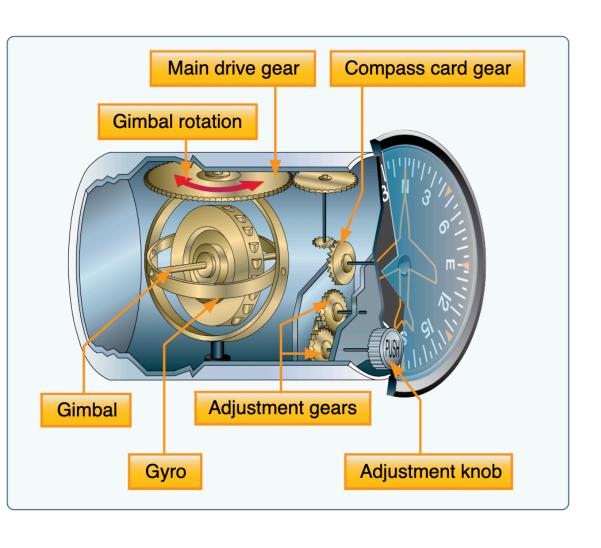
Inclinometer

- Indicates coordination of flight
- Not gyro or electrically operated
- Ball with mass in a fluid, like a level



Attitude indicator

- Indicates rotational position of the longitudinal (pitch) and lateral axis (roll)
- Adjustment knob to set horizon to level
- Pitch limit usually around 100-110°
- Bank limit around 60-70°



Directional Gyro/Heading Indicator

- Indicates rotational position about the vertical axis
- Must be continually calibrated with the magnetic compass
 - Earth rotates in space at a rate of
 15° in 1 hour
 - Gyroscopic precession: gimbal is not frictionless, small forces cause position drift



Horizontal Situation Indicator (HSI)

- Often overlay VOR CDI needles
- Some can be "slaved" to a magnetic sensing device
 - Eliminates the need to manually calibrate with the magnetic compass



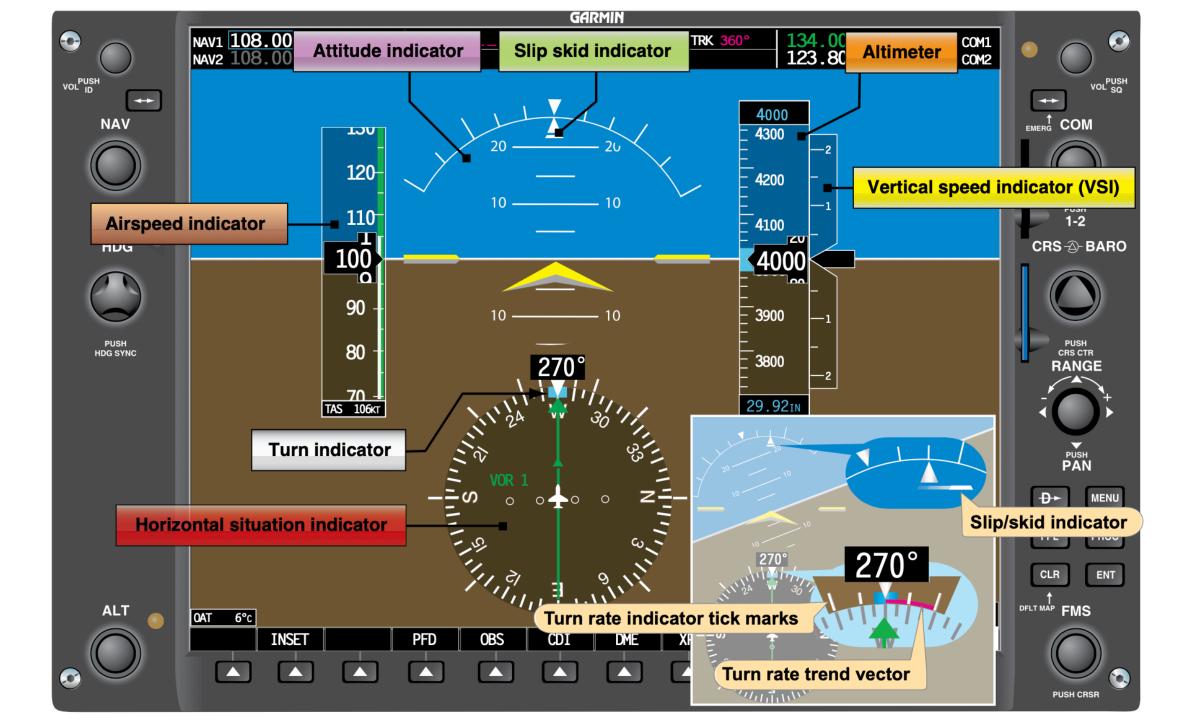
Attitude and Heading Reference System (AHRS)

- No moving parts
- Uses accelerometers for roll/pitch/yaw information
- Use a magnetometer for heading information, often mounted on the wing
- Feeds modern glass-panel displays
- Less susceptible to mechanical failures

Vacuum System Failures



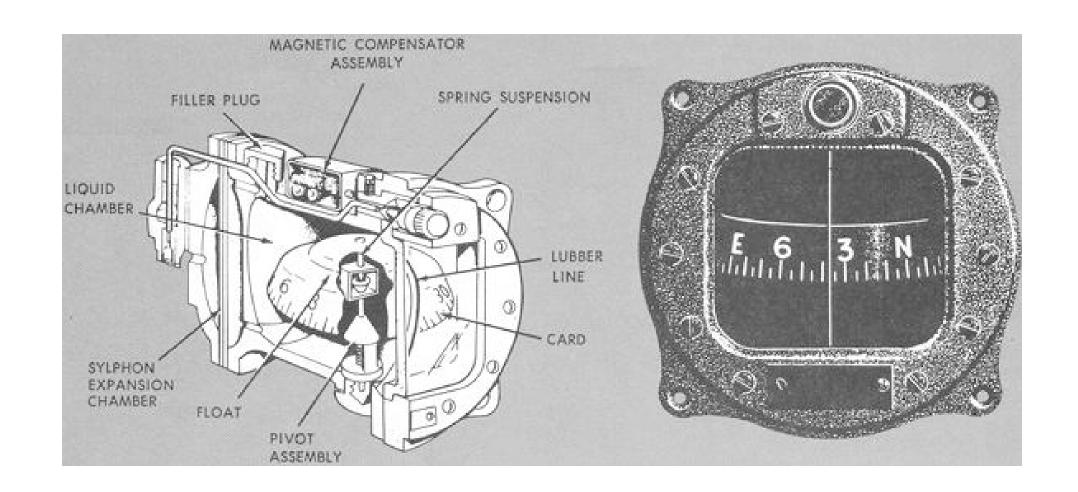
- A loss of vacuum pressure will result in a slow spin-down of gyros
- An attitude indicator will show a slow lean/dive
- Utilize a cross-checking scan





Magnetic Compass

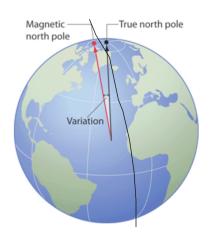
- Self-contained, no power needed
- Operates on the magnetic pull of the Earth

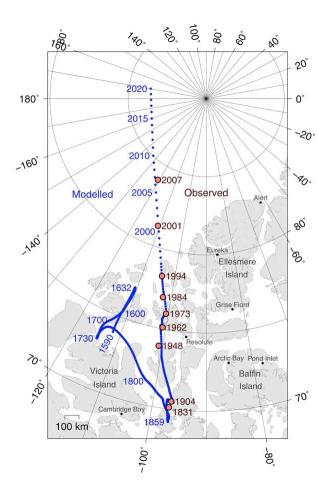


Compass Errors and Variation

- Magnetic variation: Magnetic north vs true north
- Magnetic deviation: Magnetic fields from electrical equipment in an aircraft can cause errors
- Magnetic dip errors: North and south turning errors
- Acceleration errors: Accelerating on an east/west heading

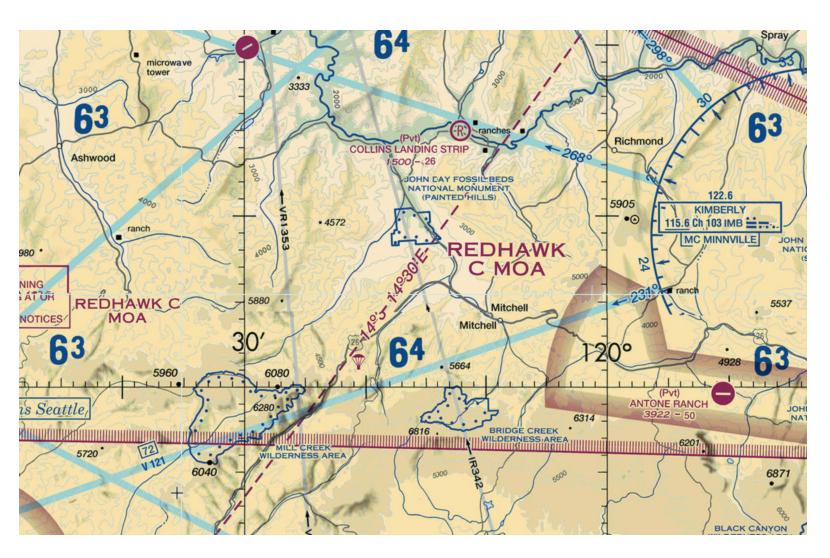
Magnetic Variation

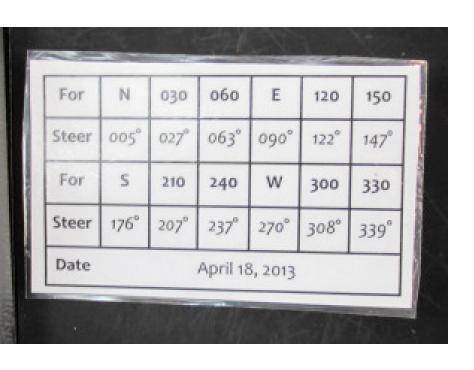




- True North and Magnetic north are not in the same spot
- The difference between true and magnetic is called variation
- This varies depending on your location on Earth

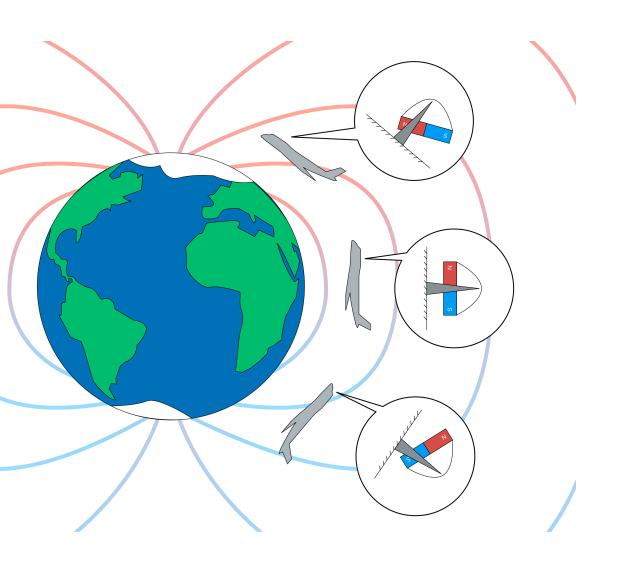
Isogonic Lines - Tells us Magnetic Variation





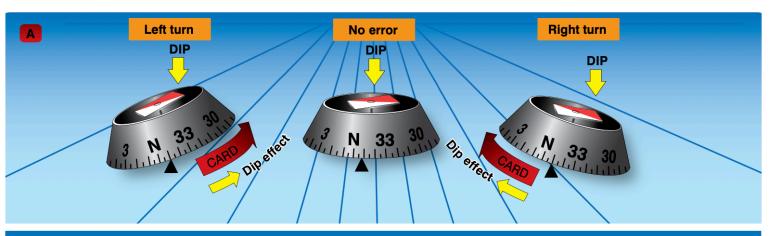
Magnetic Deviation

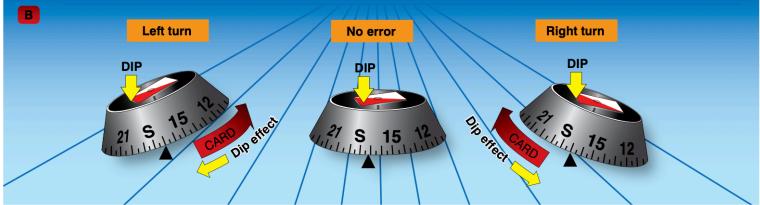
- The magnetic field for various electronic/magnetic/metallic components in the airplane can skew the direction of the compass
- The compass correction card gives you calibration to account for this
- Compass correction cards are specific to each airplane



Magnetic Dip

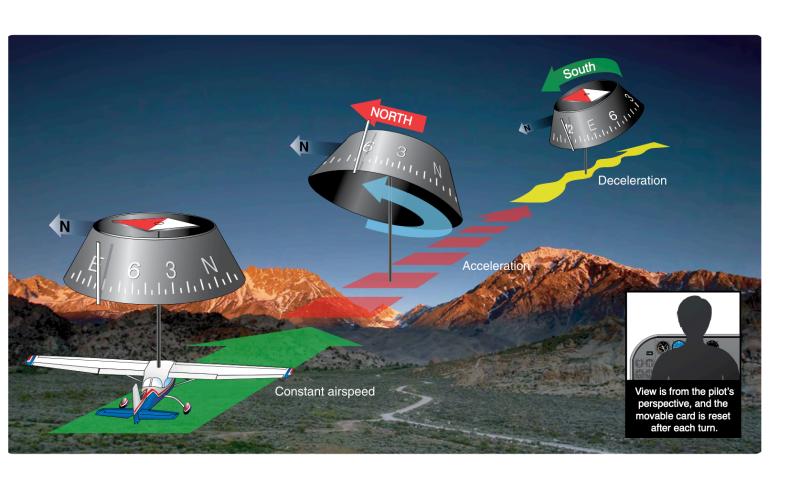
- As you get closer to the poles the vertical component of the magnetic field get stronger (and the horizontal component gets weaker)
- Compasses can compensate for this when they are level
- When they are tilted though, the results may be skew





Magnetic Dip Errors

- When turning through a N or S heading
- North: compass card leads actual heading
- South: compass card lags actual heading
- "UNOS"
 - Undershoot North
 - Overshoot South



Acceleration Errors

- Compass card is not a uniform mass
 - It's a little heavier on the north side, to account for dip
- "ANDS"

Accelerate: North

Decelerate: South

Getting an Accurate Compass Reading

- Straight and level, unaccelerated flight
- Account for deviation using the compass correction card
- Know when to use true headings vs magnetic headings
- Magnetometer-based (electronic flight displays) systems won't have these errors

Summary

- Pitot-Static instruments
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Knowledge Check

If you were to lose electrical power to the avionics bus in your airplane, which instruments would stop working?

Knowledge Check

Flying in an airplane with a vacuum system, you notice that you heading indicator is starting to drift and the attitude indicator is leaning to the left. What might this indicate?

Knowledge Check

You're turning to a heading a 360° N using the magnetic compass. How would you ensure you roll out right on your heading?